Assignment 6

Due on 2020-10-20, 23:59:59

The objective of this assignment is to

1. Design a microcontroller system for a robotic arm.
   - The robotic arm should be able to perform basic movements.
   - The system should include sensors for detecting obstacles.
   - The control system should be able to adjust its actions based on feedback.

2. Develop a mobile application for controlling the robotic arm.
   - The application should allow users to control the arm in real-time.
   - The application should display the status of the arm and its sensors.
   - The application should include a tutorial for beginners.

3. Write a report summarizing your design and implementation.
   - The report should include a detailed description of your approach.
   - The report should include a demonstration of your system in action.
   - The report should be well-organized and easy to follow.

Good luck with your assignment!

[Signature]