

$$\vec{l} = \vec{r} \times \vec{p}$$

$$\frac{\partial}{\partial t} \vec{l} = \vec{r} \times (\rho \vec{E} + \vec{j} \times \vec{B})$$

$$\frac{\partial}{\partial t} \vec{l} + \frac{1}{c^2} \vec{r} \times \vec{S} = \epsilon_0 \vec{r} \times [\vec{E} (\nabla \cdot \vec{E}) - \vec{E} \times (\nabla \times \vec{E})] + \frac{1}{\mu_0} \vec{r} \times [\vec{B} (\nabla \cdot \vec{B}) - \vec{B} \times (\nabla \times \vec{B})]$$

$$\frac{\partial}{\partial t} (\vec{l}_{\text{mech}} + \vec{l}_{\text{em}}) = \vec{r} \times (\nabla \cdot \vec{T})$$

$$\frac{d}{dt} \left( \vec{L}_{\text{mech}} + \int_{\text{Vol}} \vec{\ell}_{\text{em}} d^3x \right) = \int_{\text{Surface}} (\vec{T} \times \vec{T}) \cdot d\vec{S}$$

$$\vec{L} = \int (\vec{r} \times \frac{\vec{S}}{c^2}) 2\pi r dr$$

$$\vec{E} = -\frac{\lambda}{2\pi\epsilon_0 r} \hat{r} \quad (r < a)$$

$$\vec{p} = \frac{1}{\mu_0 c^2} \vec{E} \times \vec{B} = \frac{1}{\mu_0 c^2} \left( -\frac{\lambda}{2\pi\epsilon_0 r} \right) \hat{r} \times B_0 \hat{z}$$

$$= \frac{B_0 \lambda}{2\pi r} \hat{\phi}$$

$$\vec{L} = \frac{B_0 \lambda}{2\pi} \int_0^a \frac{\vec{r} \times \hat{\phi}}{r} 2\pi r dr = \frac{B_0 \lambda}{2\pi} \frac{a^2}{2} \hat{z}$$

$$\vec{L} = \frac{B_0 \lambda a^2}{2} \hat{z}$$

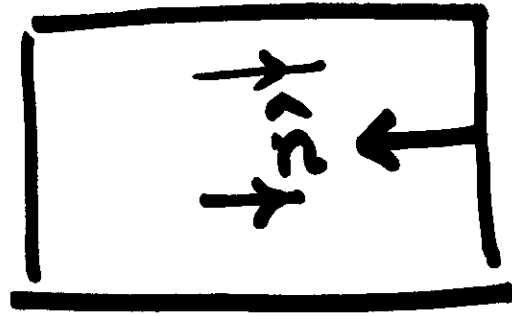
$$J_{\phi} = \frac{Q}{T} = 2\pi a \sigma \times \frac{\omega}{2\pi} = \frac{\lambda \omega}{2\pi}$$

$$\vec{B}_f = \mu_0 J \hat{z} = \mu_0 \frac{\lambda \omega}{2\pi} \hat{z}$$

$$\vec{L}_f = \frac{B_f \lambda a^2}{2} \hat{z}$$

$$= \frac{\mu_0}{4\pi} \lambda^2 a^2 \omega$$

$$I \omega + \frac{\mu_0}{4\pi} \lambda^2 a^2 \omega = \frac{B_0 \lambda^2 a^2}{2}$$



$$d\vec{F} = \vec{T} \cdot d\vec{S}$$

$$T_{xx} = \epsilon_0 \left( E_x^2 - \frac{1}{2} E^2 \right) + \frac{1}{\mu_0} \left( B_x^2 - \frac{1}{2} B^2 \right)$$

$$E_x^2 = \frac{1}{3} E^2$$

$$B_x^2 = \frac{1}{3} B^2$$

$$dF_x = \frac{1}{6} \epsilon_0 E^2 + \frac{1}{6 \mu_0} B^2$$

$$= \frac{1}{3} \left( \frac{1}{2} \epsilon_0 E^2 + \frac{1}{2} \frac{B^2}{\mu_0} \right) = \frac{2}{3} \mu$$

$$\vec{\nabla} \cdot \vec{E} = 0$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\nabla \times \vec{B} = \mu \epsilon \frac{\partial \vec{E}}{\partial t}$$

$$\nabla \times (\nabla \times \vec{E}) = -\frac{\partial}{\partial t} (\nabla \times \vec{B})$$

$$\nabla (\vec{\nabla} \cdot \vec{E}) - \nabla^2 \vec{E} = -\frac{\partial}{\partial t} (\mu \epsilon \frac{\partial \vec{E}}{\partial t})$$

$$\nabla^2 \vec{E} = \mu \epsilon \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\nabla^2 \vec{B} = \mu \epsilon \frac{\partial^2 \vec{B}}{\partial t^2}$$

$$\vec{E} = \vec{E}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

$$\vec{B} = \vec{B}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

$$\vec{k} \cdot \vec{r} - \omega t = \text{Constant} \Rightarrow \xi = \vec{k} \cdot \vec{r} = \text{Const}$$

$$- \omega t + |\vec{k}| \xi = \text{Const}$$

$$|\vec{k}| \frac{d\xi}{dt} = \omega, \quad \frac{d\xi}{dt} = \frac{\omega}{k} = v$$

$$\nabla \cdot \vec{E} = 0 \Rightarrow \vec{k} \cdot \vec{m} = 0$$

$$\nabla \cdot \vec{B} = 0 \Rightarrow \vec{k} \cdot \vec{m} = 0$$

$$\nabla \times \vec{B} = \mu \epsilon \frac{\partial \vec{m}}{\partial t}$$

$$\nabla \rightarrow i\vec{k}$$
$$\frac{\partial}{\partial t} \rightarrow -i\omega$$

$$i\vec{k} \times \vec{B} = -i\omega \mu \epsilon \vec{m}$$

$$\vec{k} \times (\vec{k} \times \vec{B}) = -\omega \mu \epsilon \vec{k} \times \vec{m}$$

$$\vec{k} (\vec{k} \cdot \vec{B}) - \vec{B} k^2 = -\omega \mu \epsilon \vec{k} \times \vec{m}$$

$$\vec{B} = \frac{\omega \mu \epsilon \vec{k} \times \vec{m}}{k^2}$$

$$= \frac{\omega \mu \epsilon}{\omega^2} \vec{k} \times \vec{m}$$
$$= \frac{1}{\omega^2} \vec{k} \times \vec{m}$$

$$\mu \epsilon = \frac{1}{\omega^2}$$



$$\begin{aligned}
 \vec{m}_b \times \vec{m}_b &= \vec{0} \\
 \vec{m}_b \times \vec{k} &= \vec{m}_a \\
 \vec{k} \times \vec{m}_a &= \vec{0}
 \end{aligned}$$

$\{ \vec{m}_a, \vec{m}_b, \vec{k} \}$

Right Handed Triad



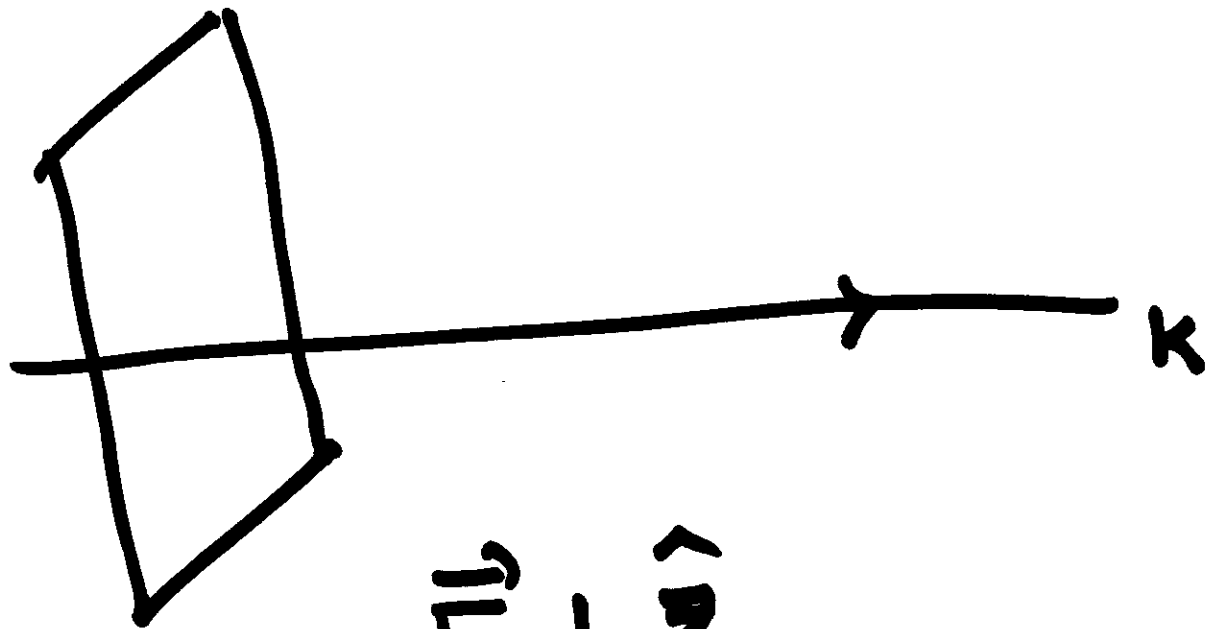
$$\begin{aligned}
 u &= \frac{1}{2} \epsilon E^2 + \frac{B^2}{2\mu} \\
 &= \frac{1}{2} \epsilon \left[ E^2 + \frac{B^2}{\mu \epsilon} \right] \\
 &= \frac{1}{2} \epsilon \left[ E^2 + \underline{v^2 B^2} \right] \\
 &= \epsilon E^2
 \end{aligned}$$

$$|\vec{S}| = |\vec{E} \times \vec{H}| = \frac{EB}{\mu_0} = c \epsilon_0 E^2$$

$$\vec{S} = c \epsilon_0 E_0^2 \underline{\cos^2(kz - \omega t)} \hat{k}$$

$$I = \langle \vec{S} \rangle = \frac{1}{2} c \epsilon_0 E_0^2 \hat{k}$$

# Polarization



$$\vec{E}(z,t) = \text{Re} \left[ (\underline{E}_{0x} \hat{z} + \underline{E}_{0y} \hat{y}) e^{-i\omega t + ikz} \right]$$

$\vec{E} \perp \hat{z}$

$$E_{0x} = |E_{0x}| e^{i\varphi}$$

$$E_{0y} = |E_{0y}| e^{i\varphi}$$

$$\vec{E} = (|E_{0x}| \hat{i} + |E_{0y}| \hat{j}) \cos(kz - \omega t + \varphi)$$

Linearly polarized

$$E_{0x} = |E_{0x}|$$

$$E_{0y} = |E_{0y}| e^{i\varphi}$$

Elliptically polarized

$$\varphi = \frac{\pi}{2}$$

$$|E_{0x}| = |E_{0y}| \quad \odot \text{ or } \ominus$$