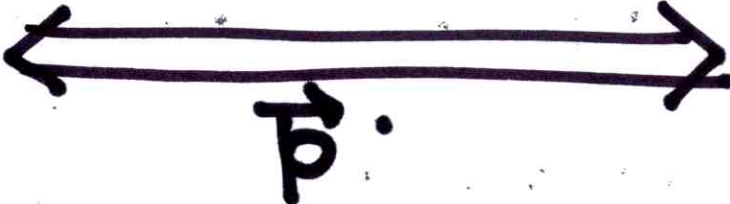
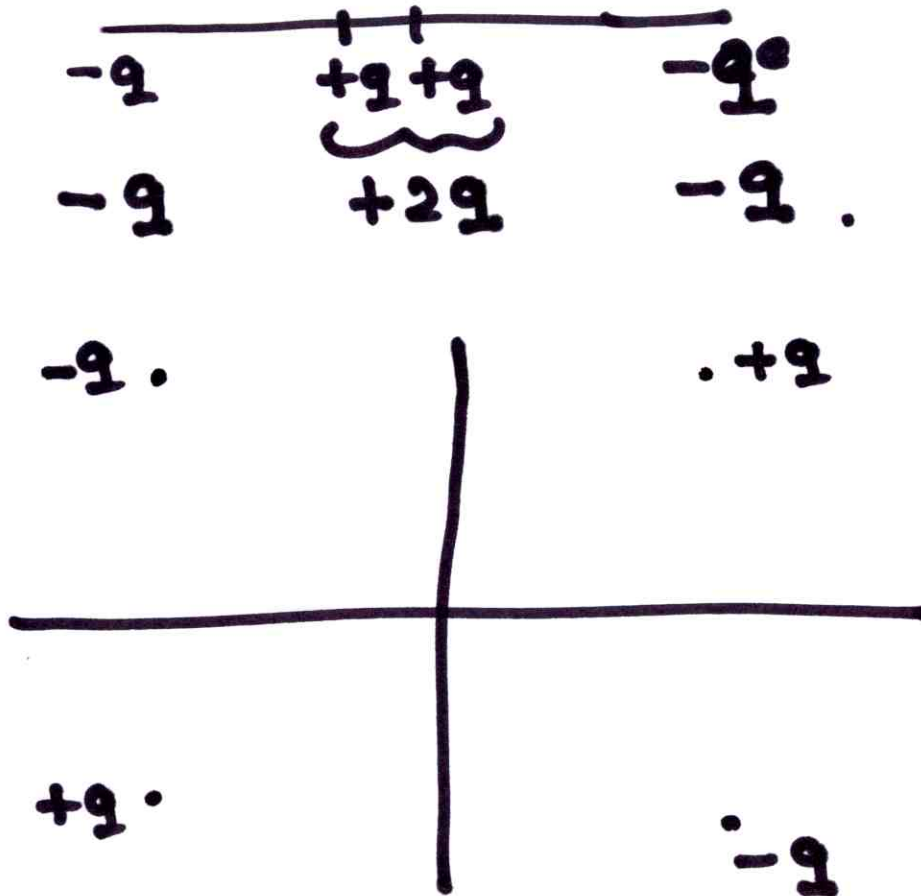


$$\int \vec{r}' \rho(r') d^3r'$$


A horizontal double-headed arrow pointing left and right, with the vector symbol  $\vec{p}$  centered below it.



Linear Quadrupole

$$\vec{P} = \int \rho(\vec{r}) \vec{r} d^3r.$$

$$\vec{r}' = \vec{r} + \vec{a}.$$

$$\vec{P} = \int \rho(\vec{r}') (\vec{r}' - \vec{a}) d^3r'.$$

$$= \int \rho(\vec{r}') \vec{r}' d^3r' - \vec{a} \int \rho(\vec{r}') d^3r'.$$

$$\text{If } Q = 0$$

$\vec{P}$  is independent of origin.

$$\rho_b = -\vec{\nabla} \cdot \vec{P}$$

$$q_b = \vec{P} \cdot \hat{z}$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} = \frac{\rho_f + \rho_b}{\epsilon_0}$$

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P}$$

$$\vec{\nabla} \cdot \vec{D} = \epsilon_0 \vec{\nabla} \cdot \vec{E} + \vec{\nabla} \cdot \vec{P}$$

$$= \epsilon_0 \cdot \frac{\rho_f + \rho_b}{\epsilon_0} - \rho_b = \rho_f$$

$$E = E_0 \hat{z}$$

$$\phi_{\text{ext}} = -E_0 r \cos \theta \quad (\text{At large distances}).$$

$$\phi_1(r, \theta) = A_1 r \cos \theta + \frac{B_1}{r^2} \cos \theta.$$

$$\phi_2(r, \theta) = A_2 r \cos \theta$$

$$A_1 = -E_0$$

$$-E_0 a + \frac{B_1}{a^2} = A_2 a$$



$$D_{in} = \frac{1}{4\pi} \left( -\frac{\partial \phi_1}{\partial z} \right)$$

$$= \frac{1}{4\pi} \left[ -\frac{\partial}{\partial z} \left[ \frac{(-\frac{1}{2}) 2(z-d)q}{[(z-d)^2 + \rho^2]^{3/2}} + \frac{2(z+d)q'(-\frac{1}{2})}{[(z+d)^2 + \rho^2]^{3/2}} \right] \right]$$

$$= \frac{1}{4\pi} \left[ \frac{(-\frac{1}{2}) 2(z-d)q}{[(z-d)^2 + \rho^2]^{3/2}} + \frac{2(z+d)q'(-\frac{1}{2})}{[(z+d)^2 + \rho^2]^{3/2}} \right]$$

$$\int \vec{\nabla} \cdot \vec{D} d^3r = \int \rho_f d^3r$$

$$\oint \vec{D} \cdot d\vec{s} = Q_{\text{free}}$$