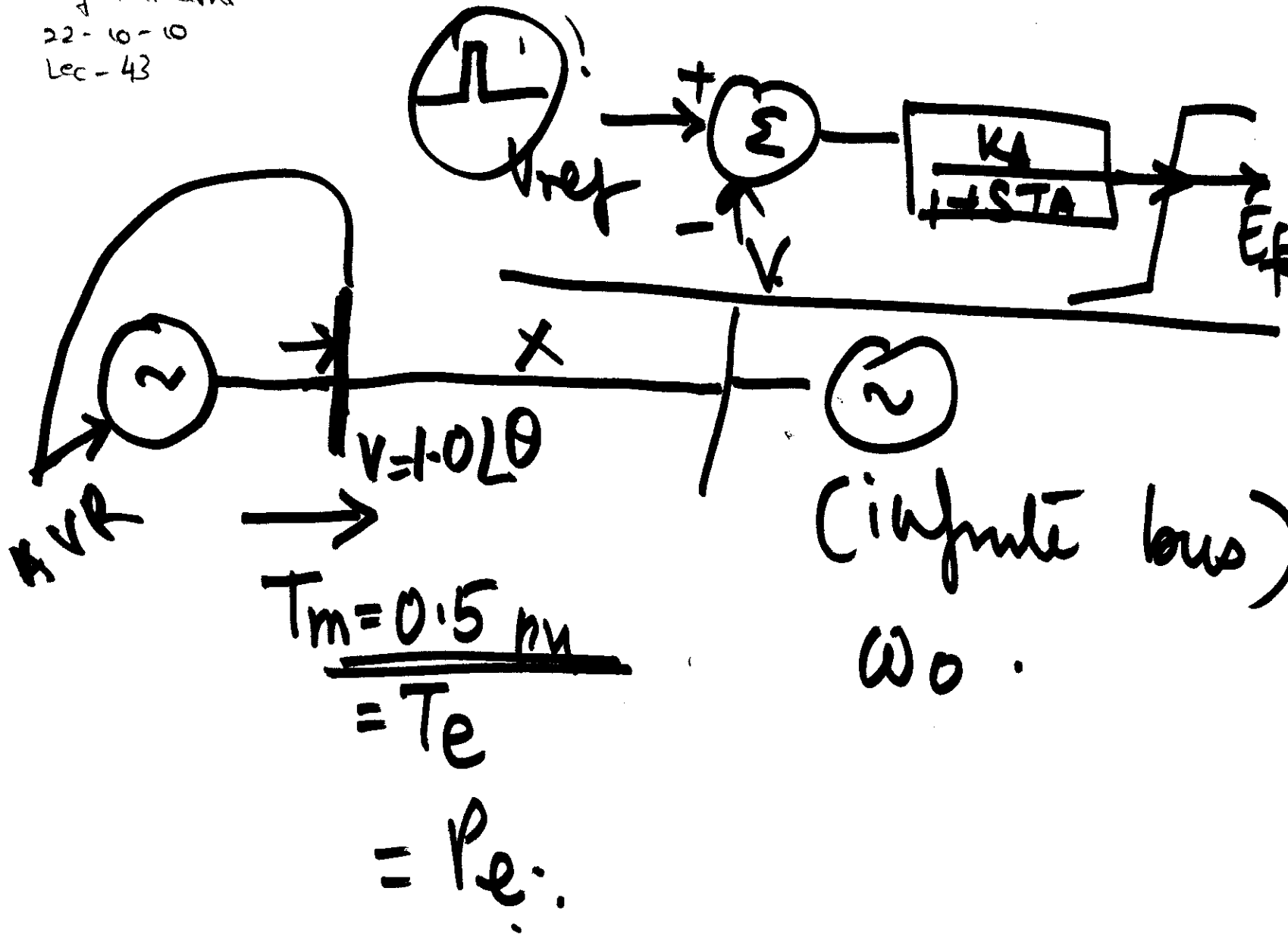
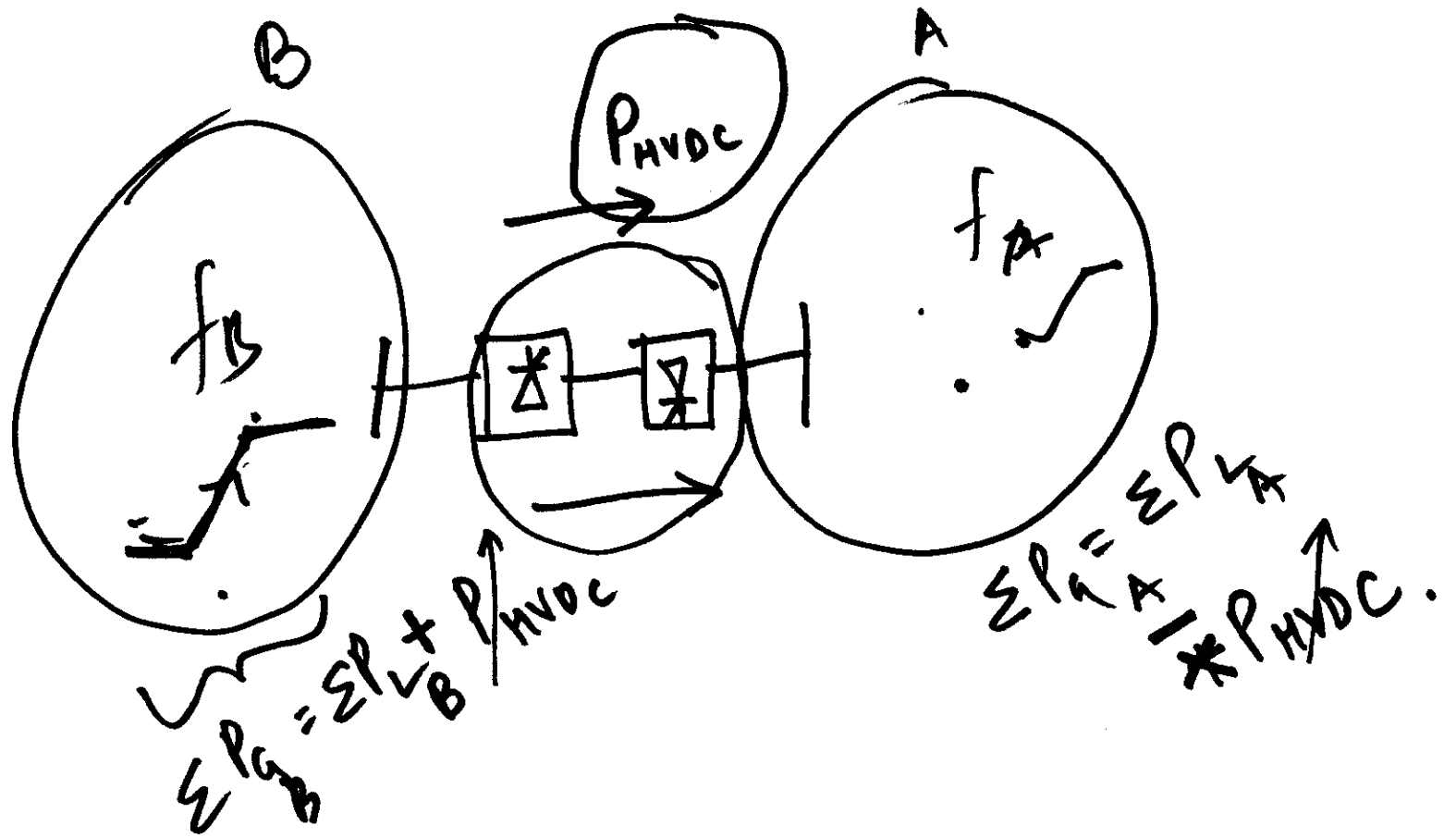
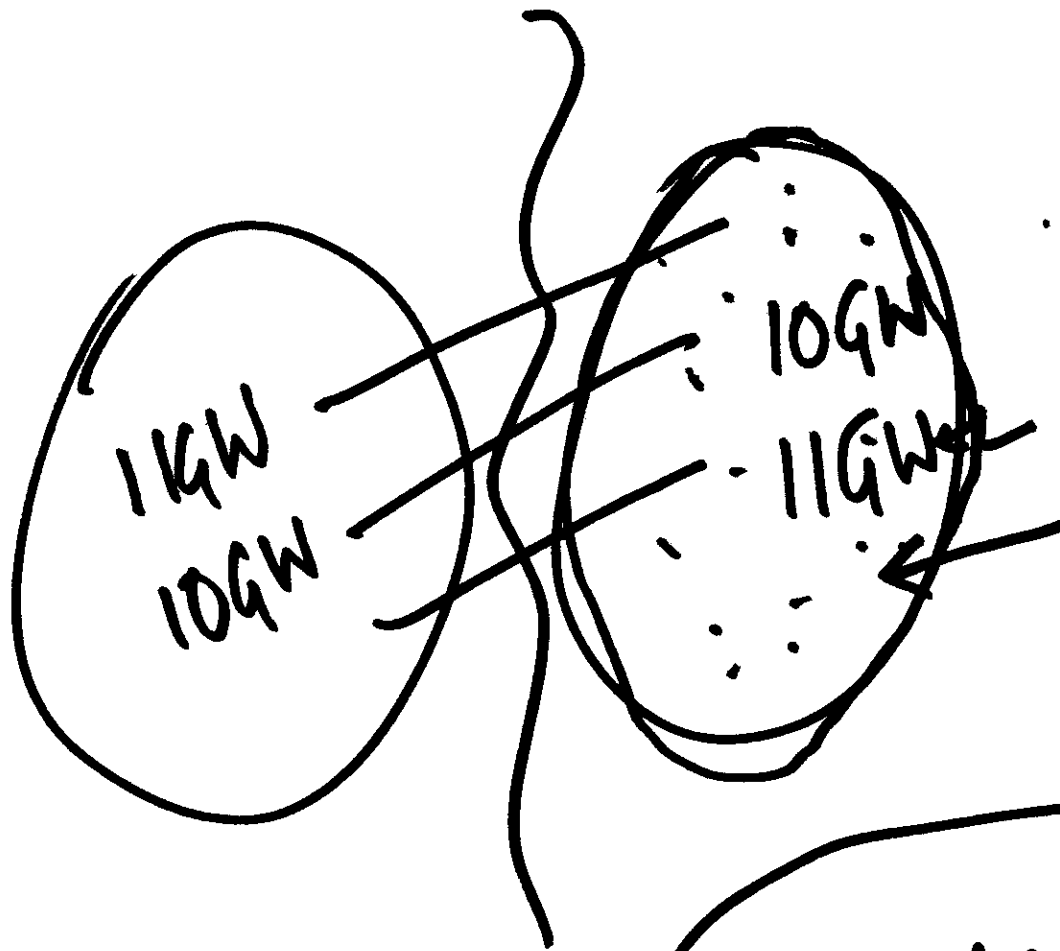


Prof. Kulkarni
22-10-10
Lec-43





Async. connections
 between A & B.



$$\underline{w_{ov}(t)} = \frac{\sum H_i \overset{\downarrow}{w_i(t)}}{\sum H_i}$$

$$\frac{2(\sum H_i)}{\omega_B} \frac{d\omega_{coi}}{dt} = \sum P_m - \sum P_e$$

$$\underbrace{\hspace{10em}} = \sum P_m - \underbrace{\sum P_L}_{\text{losses}}$$

= imbalance

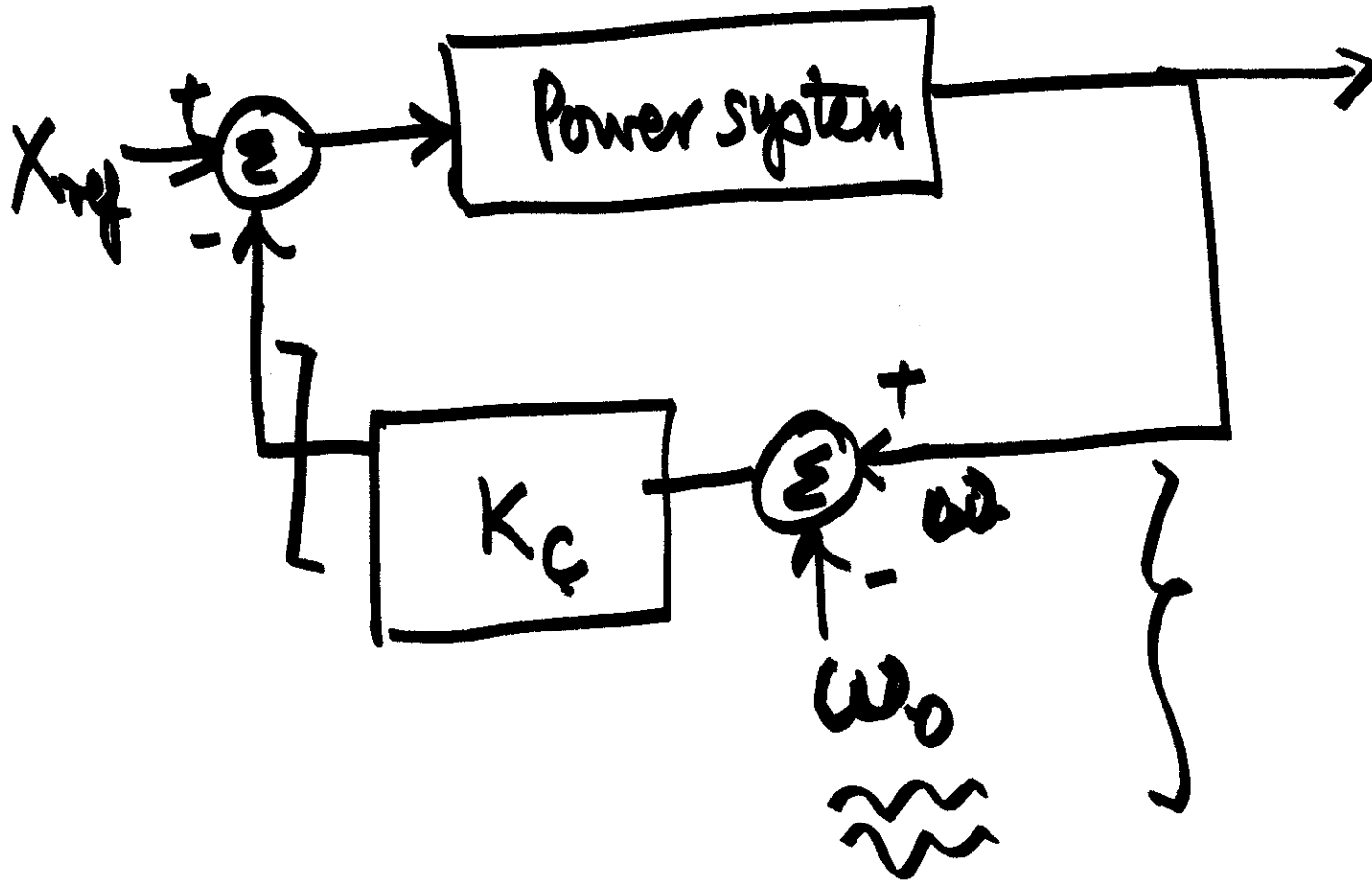
$$\omega_{coi}(t) = \frac{\sum H_i \omega_i(t)}{\sum H_i}$$

$$\sum P_e = \sum P_L + \text{losses.}$$

Prof. Arun Kumar
Date - 29/10/20

$$\Delta X \rightarrow -K_c (\omega - \omega_0)$$

X inductive reactance



$$\frac{d\Delta\delta}{dt} = \Delta\omega$$

$$\frac{2H}{\omega_B} \frac{d\Delta\omega}{dt} = -K \Delta\delta - \frac{\partial P_e}{\partial X} \Delta X.$$

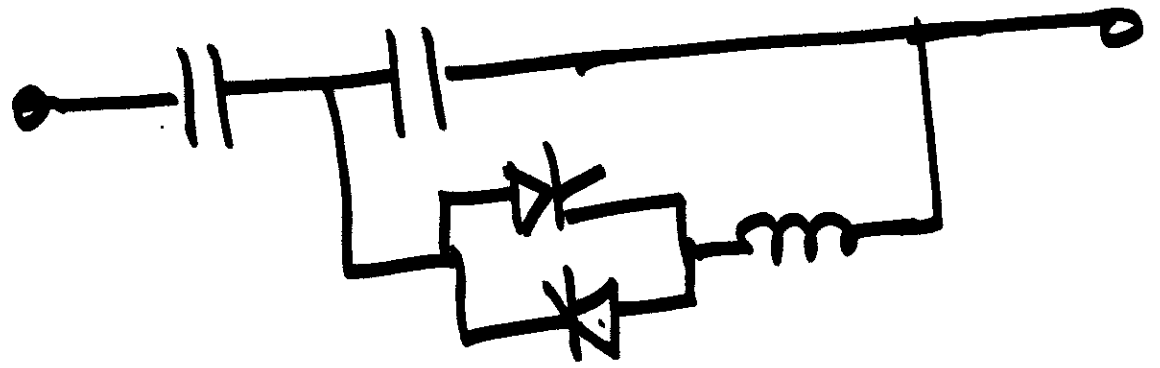
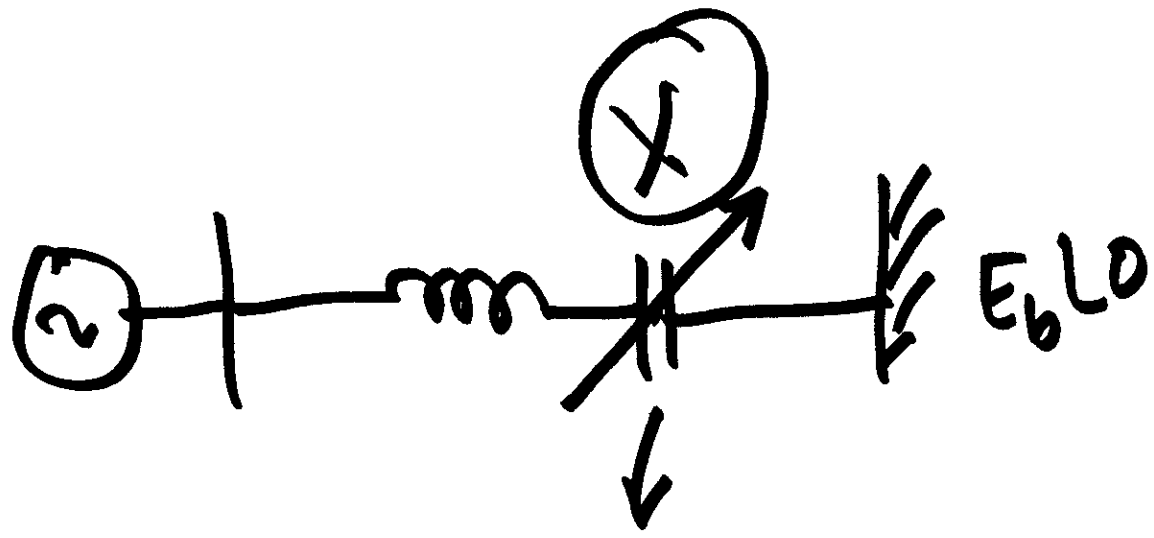
$$P_e = \frac{E E_b \sin\delta}{X}$$

$$\frac{\partial P_e}{\partial X} = -\frac{E E_b \sin\delta}{X^2}$$

$$P_e = K_1 \sin \delta = \frac{E E_b \sin \delta}{\cancel{\Delta x}}$$

$$\frac{d \Delta \delta}{dt} = \Delta \omega$$

$$\frac{2H}{\omega_B} \frac{d \Delta \omega}{dt} = -\Delta P_e = -\frac{\partial P_e}{\partial \delta} \bigg|_{\Delta \delta} - \frac{\partial P_e}{\partial \Delta x} \bigg|_{\Delta x}$$




$$\frac{d\Delta\delta}{dt} = \Delta\omega$$

$$\frac{2H}{\omega_0} \frac{d\Delta\omega}{dt} = -K\Delta\delta - \left(\frac{-E E_b \sin\delta_e}{x_e^2} \right)$$

$$= \overset{\approx 0}{-K\Delta\delta} - \overset{\approx 0}{D\Delta\omega} \quad \times \left[-K_c(\omega - \omega_0) \right]$$

↑
 $\Delta\omega$



$$\frac{d\Delta\delta}{dt} = \Delta\omega$$

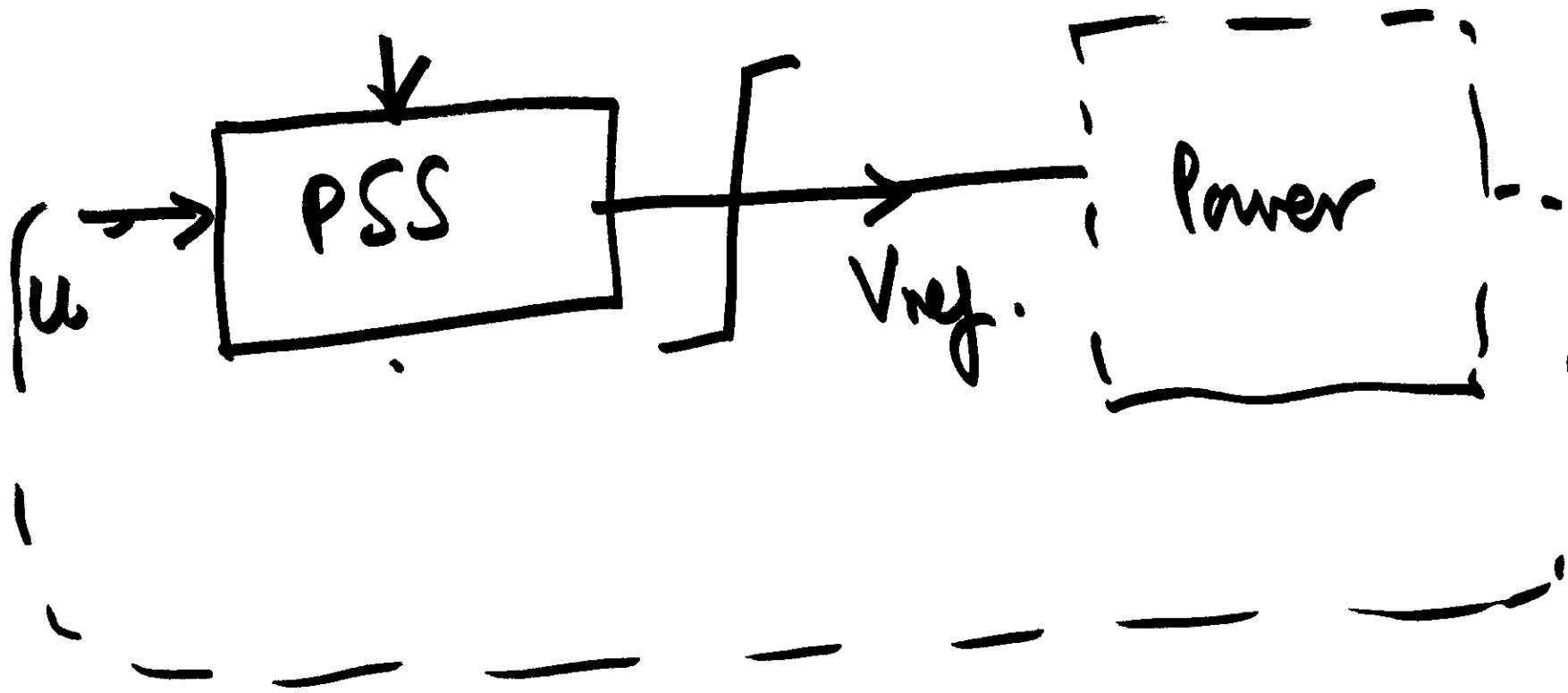
$$P_e = K_1 \sin\delta$$

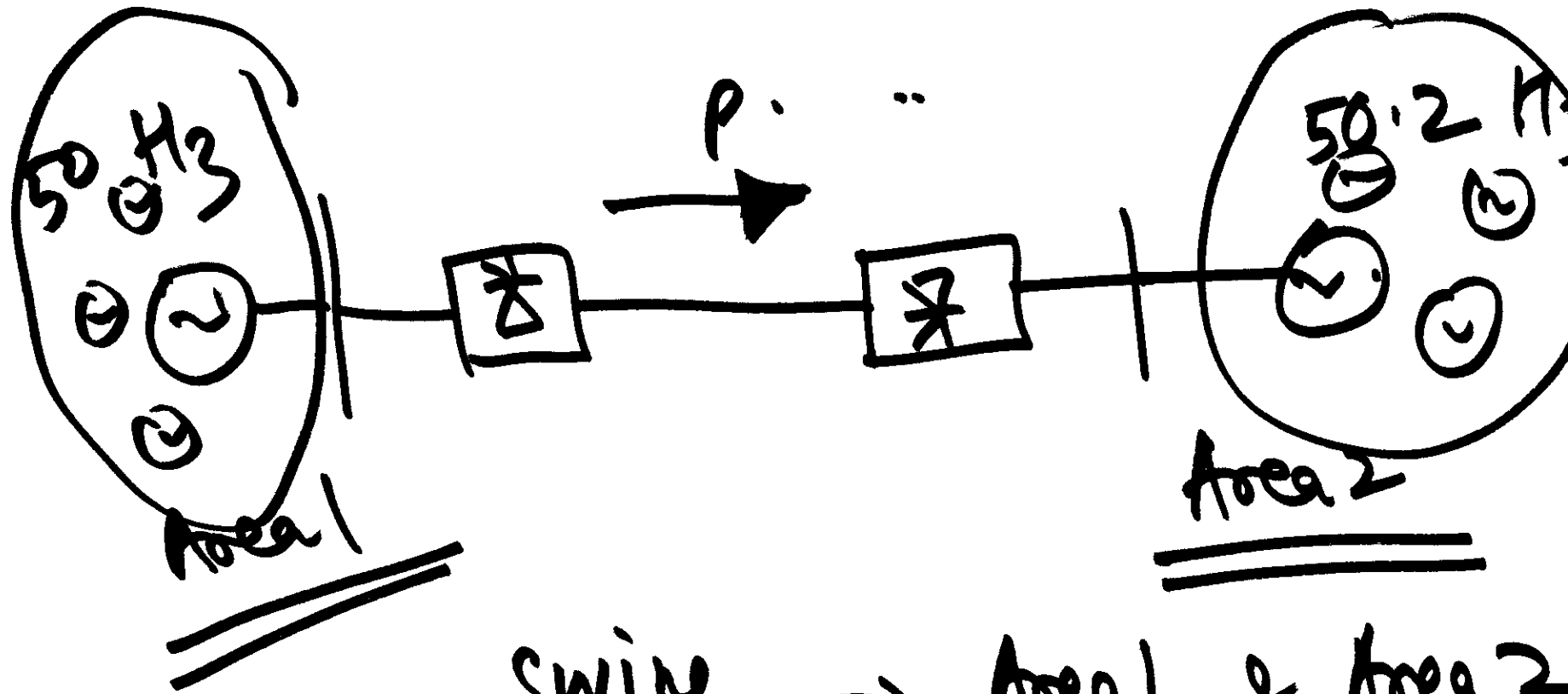
$$K_1 = \frac{\check{E} \check{E}_b}{\textcircled{X}}$$

$$\frac{2H}{\omega_B} \frac{d\omega}{dt} = P_m - P_e$$

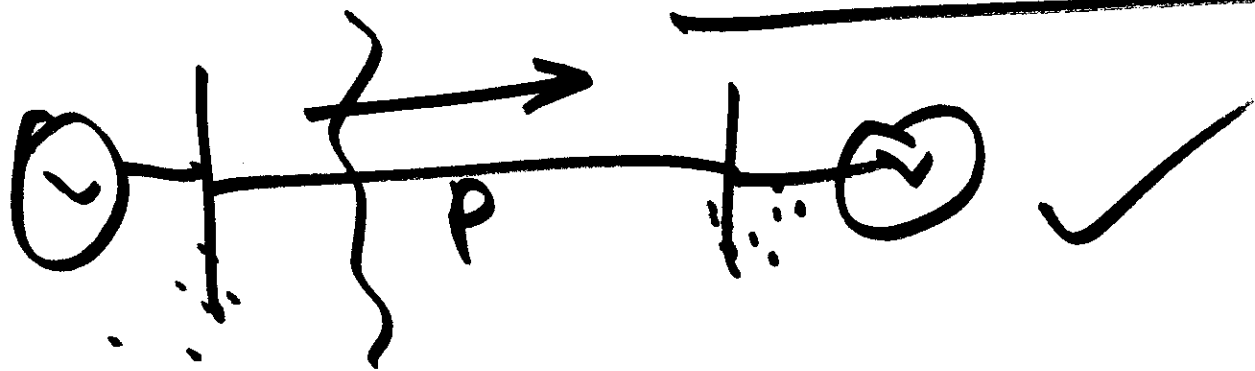
$$\frac{2H}{\omega_B} \frac{d\Delta\omega}{dt} = - \left. \frac{\partial P_e}{\partial \delta} \right|_{\delta=\delta_e} \Delta\delta$$

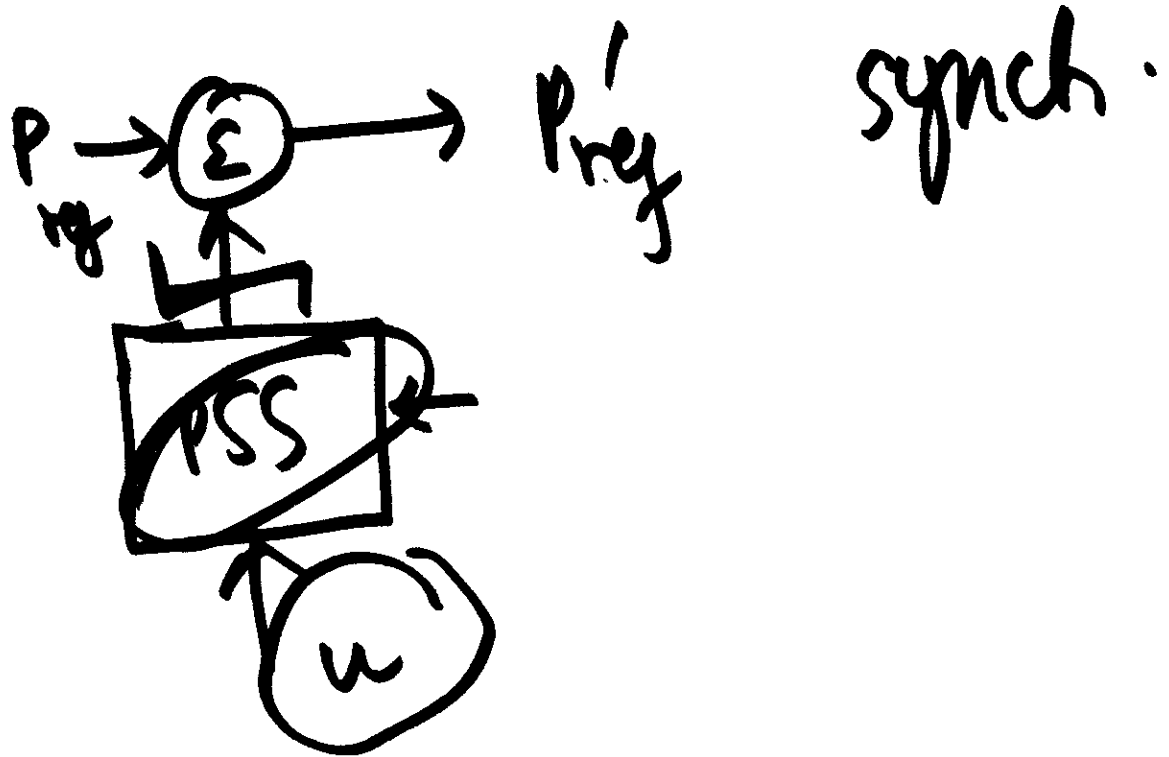
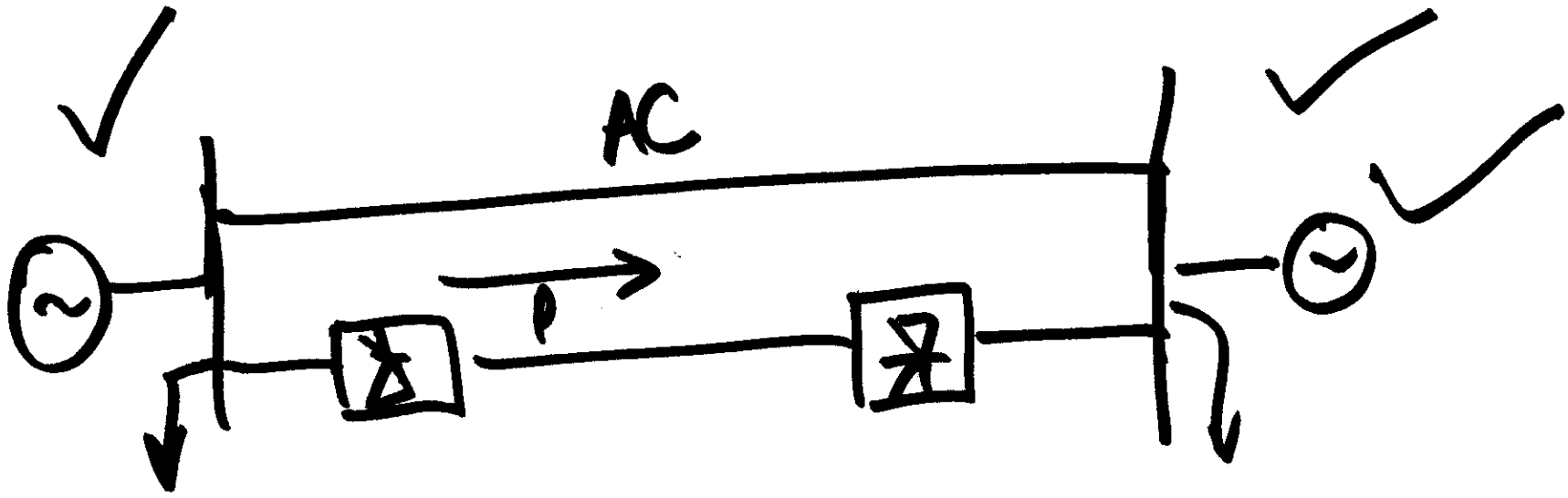
$$K = \underline{\underline{K_1 G_{\delta}}}$$

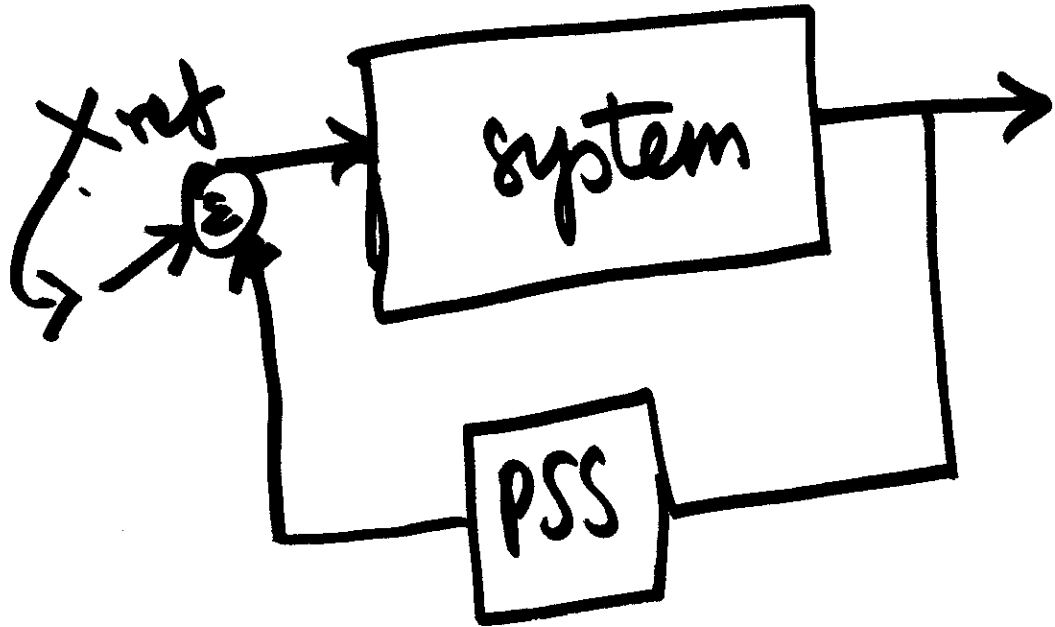
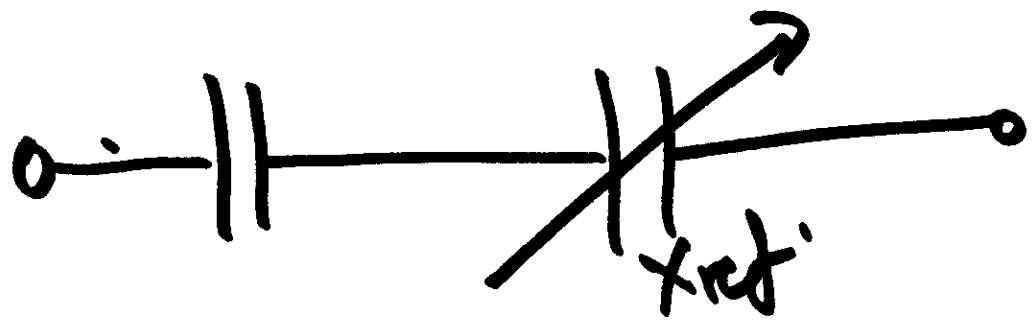


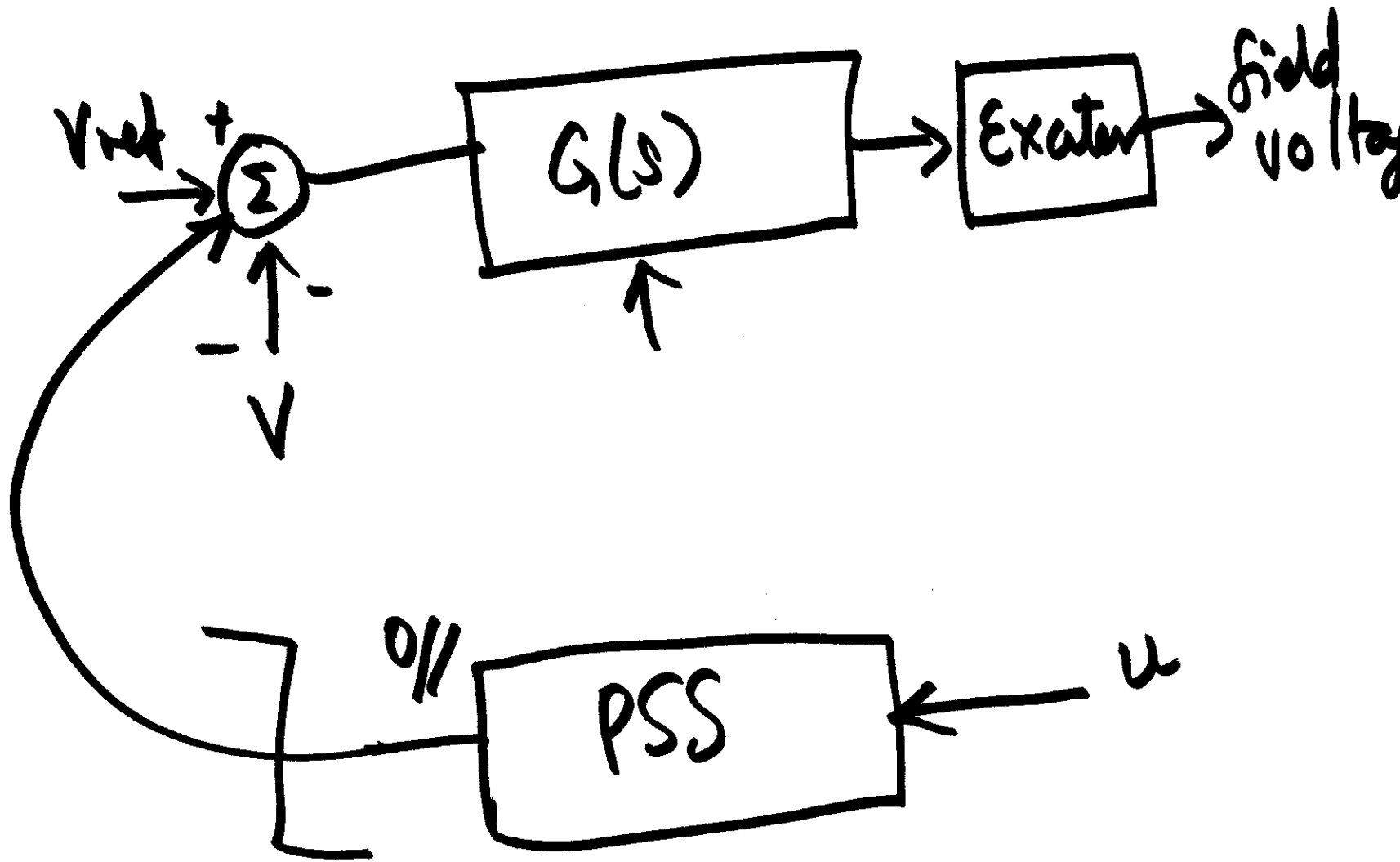


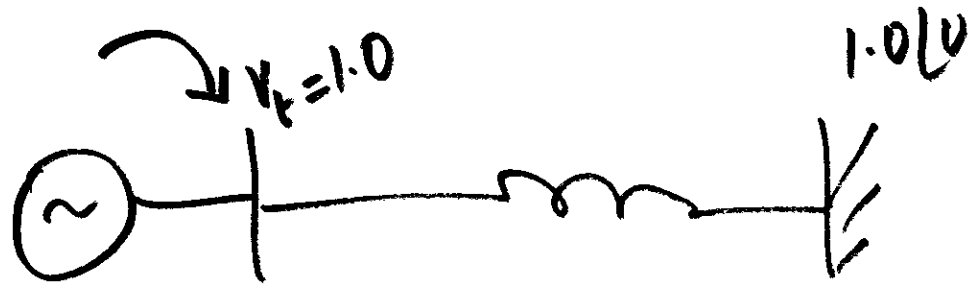
Swing \rightarrow Area 1 & Area 2











AVR

0.8 pu

0.8 pu

$$\Delta \tilde{x} = \left. \frac{\partial f}{\partial x} \right|_{x=x_c} \Delta x + \left. \frac{\partial f}{\partial u} \right|_{x=x_c} \Delta u$$

$\underbrace{\qquad\qquad\qquad}_{V_{ref}} \quad \underbrace{\qquad\qquad\qquad}_{\text{ref}}$

$$\tilde{x} = f(x, u)$$

