

Basic Concepts

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Objectives of This Module

- This module gives evolution of Distributed Computing Systems (DCS) from hardware and software infrastructure point of view.
- This module also discusses what are the design goals, transparencies and fundamental issues in DCS
- Comparison of various Operating Systems from historical point of view is discussed

Road Map

- Generic Component (H/W) of Distributed Computing System:
 - Computer system
 - Networking
- Evolution of operating systems
- Introduction to distributed computing systems (DCS)

Generic Components (H/W) of a DCS

- (1) Computer System

- CISC

- Complex instruction set computer
- A single instruction performs multiple actions (hence complex in operation)
- Ex: VAX, Intel® X86, IBM 360/370

- RISC

- Reduced instruction set computer
- Each instruction performs only a simple operation
- Ex: MIPS, DEC Alpha, SUN Sparc, IBM 801

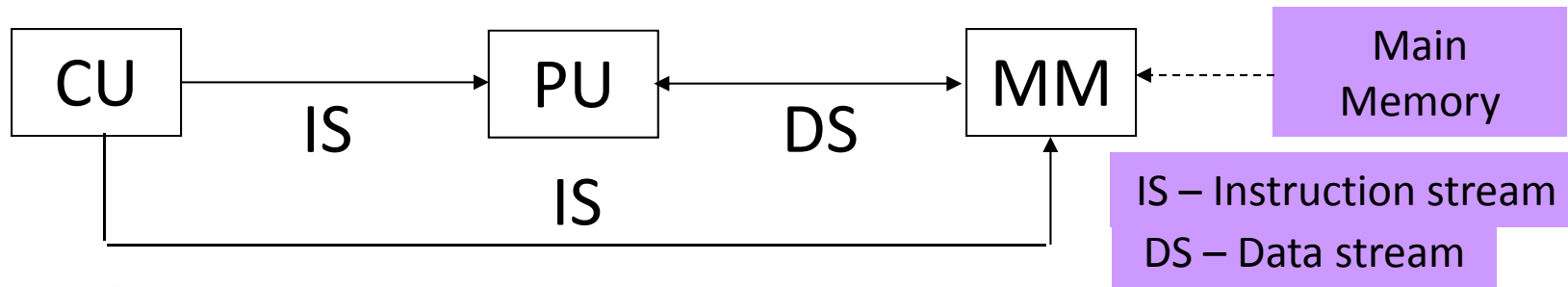
- Multi Core

- More processors on chip, so multiple instructions can run at the same time
- Intel Core Duo, Intel i3, i5, i7, AMD Phenom II X4

Flynn's Classification of Computer System

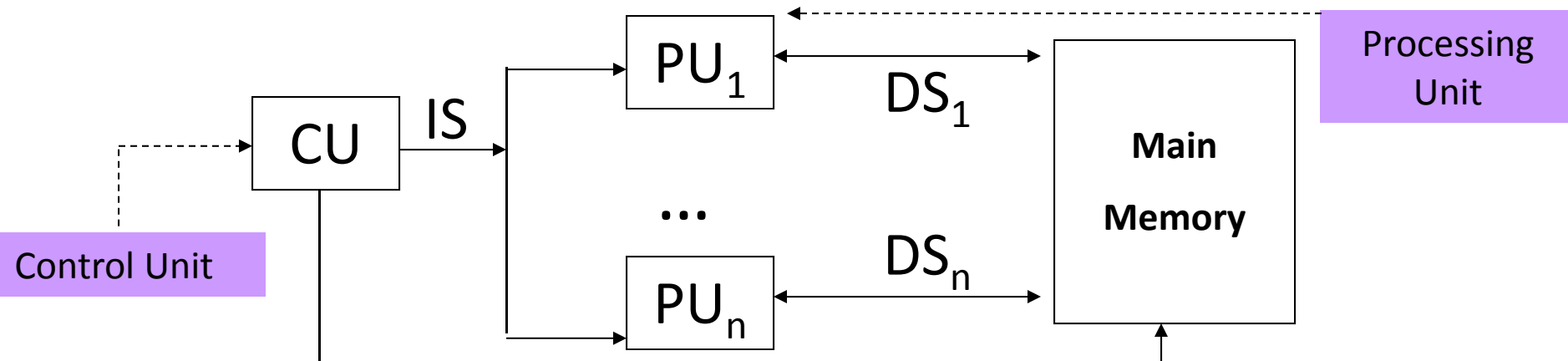
- **SISD (Single Instruction Single Data)**

- General purpose computer



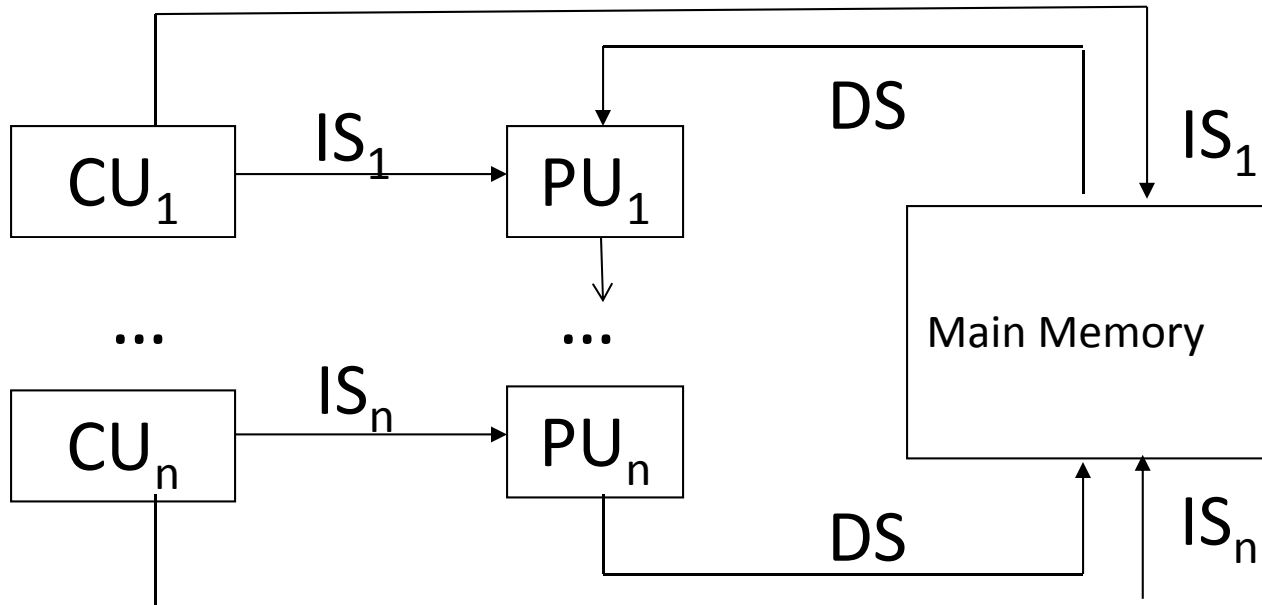
- **SIMD (Single Instruction Multiple Data)**

- Vector processing computer



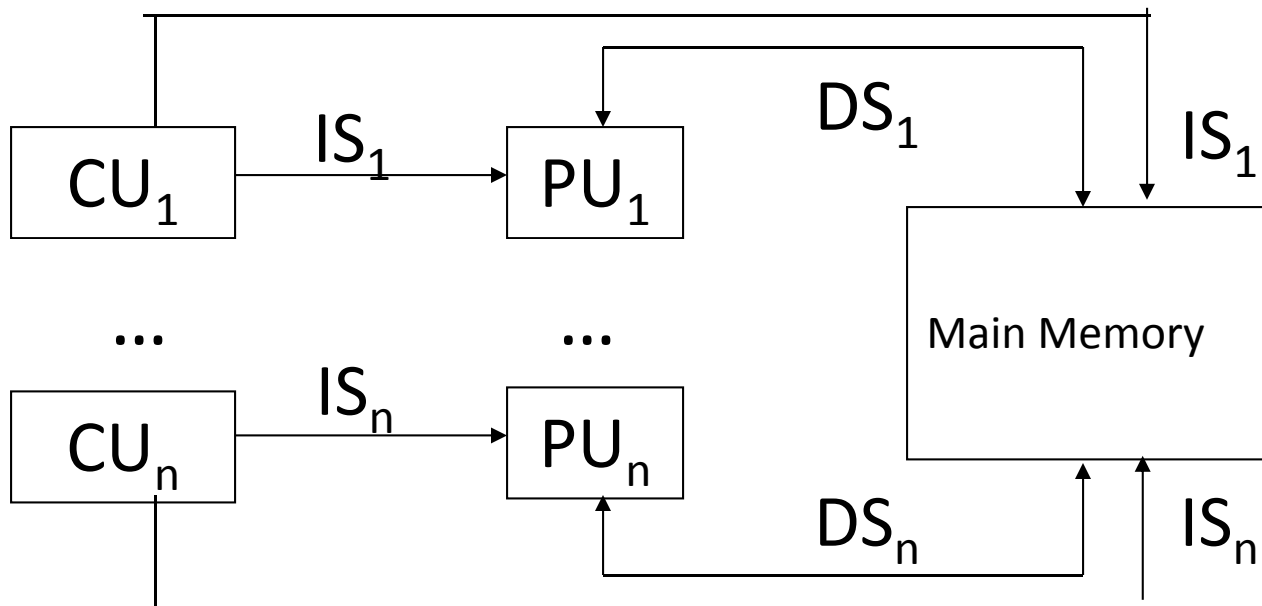
Flynn's Classification Contd...

- MISD (Multiple Instruction Single Data)



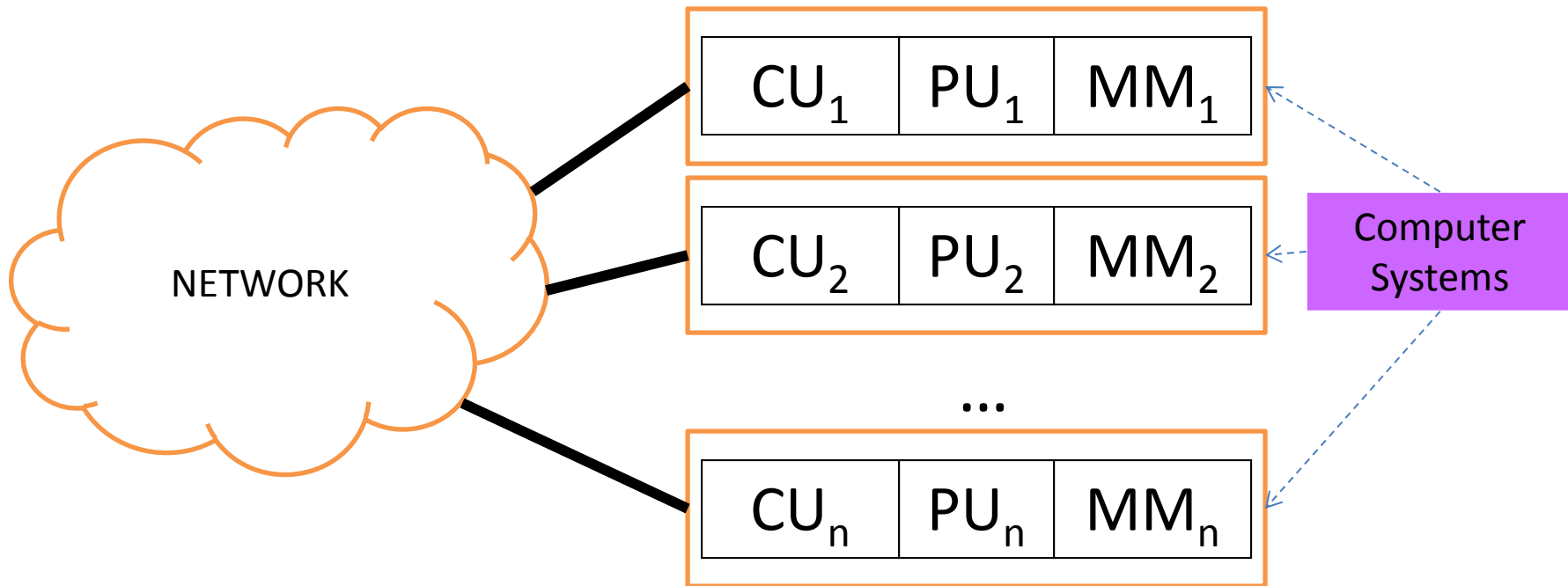
Flynn's Classification Contd...

- **MIMD (Multiple Instruction Multiple Data)**
 - Multi Processor with shared Memory



• MIMD (Multiple Instruction Multiple Data)

- Multi Processor with non-shared memory
- Communication is by passing messages between them via network



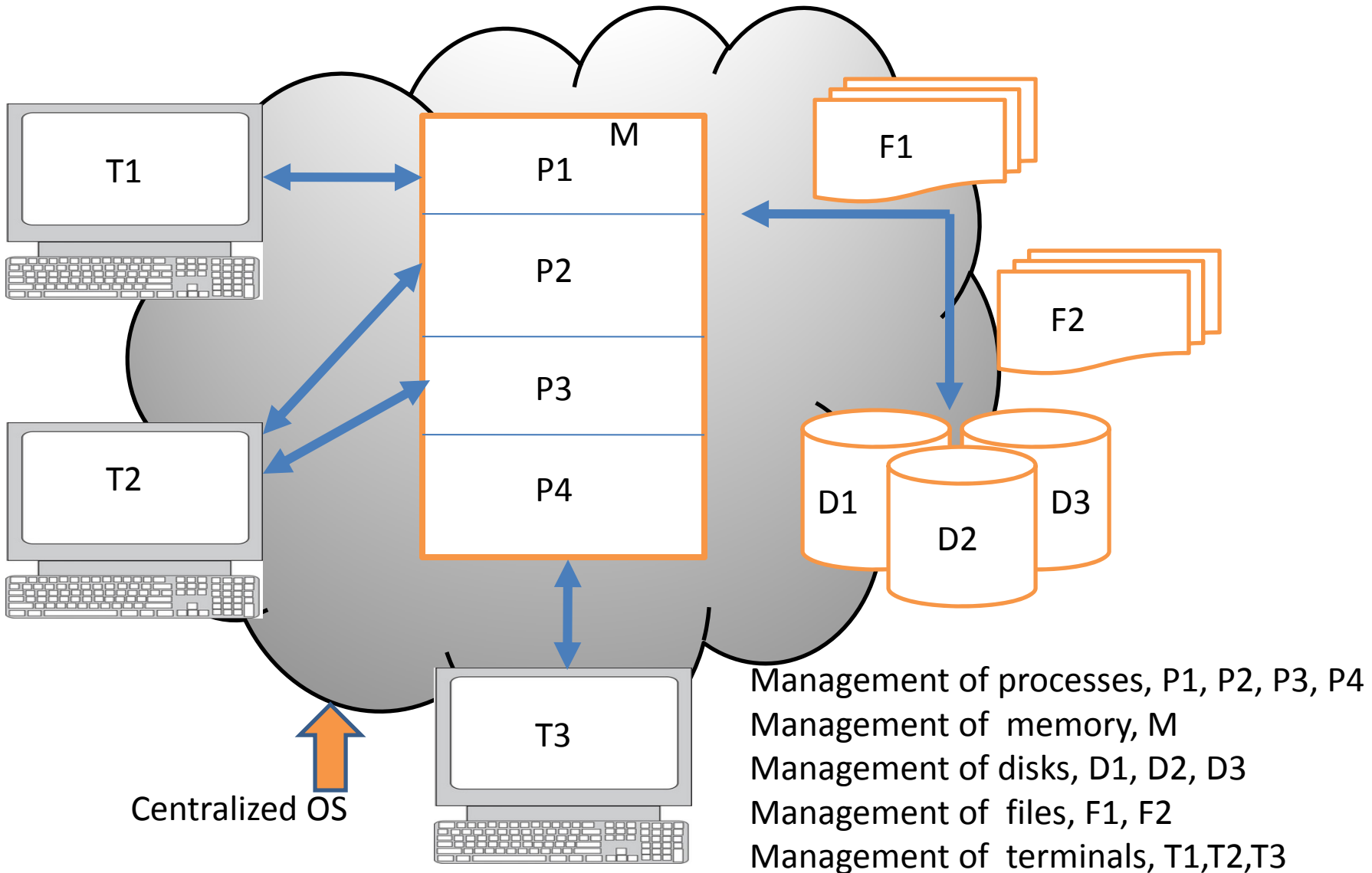
Generic Components (H/W) of a DCS

- (2) Networking
 - Interconnected heterogeneous computer system which can exchange information.
 - LAN: connects computers at single location and normally owned by single organization.
 - INTERNET: a world-wide collection of thousands of interconnected computers and no one own it.
- DCS is networked computers providing single computer view to the user.

Evolution of Modern OS

- First generation OS
 - System :
 - Centralized OS
 - Characteristics :
 - Process Management
 - Memory Management
 - I/O Management
 - File Management.
 - Goals :
 - Resource Management

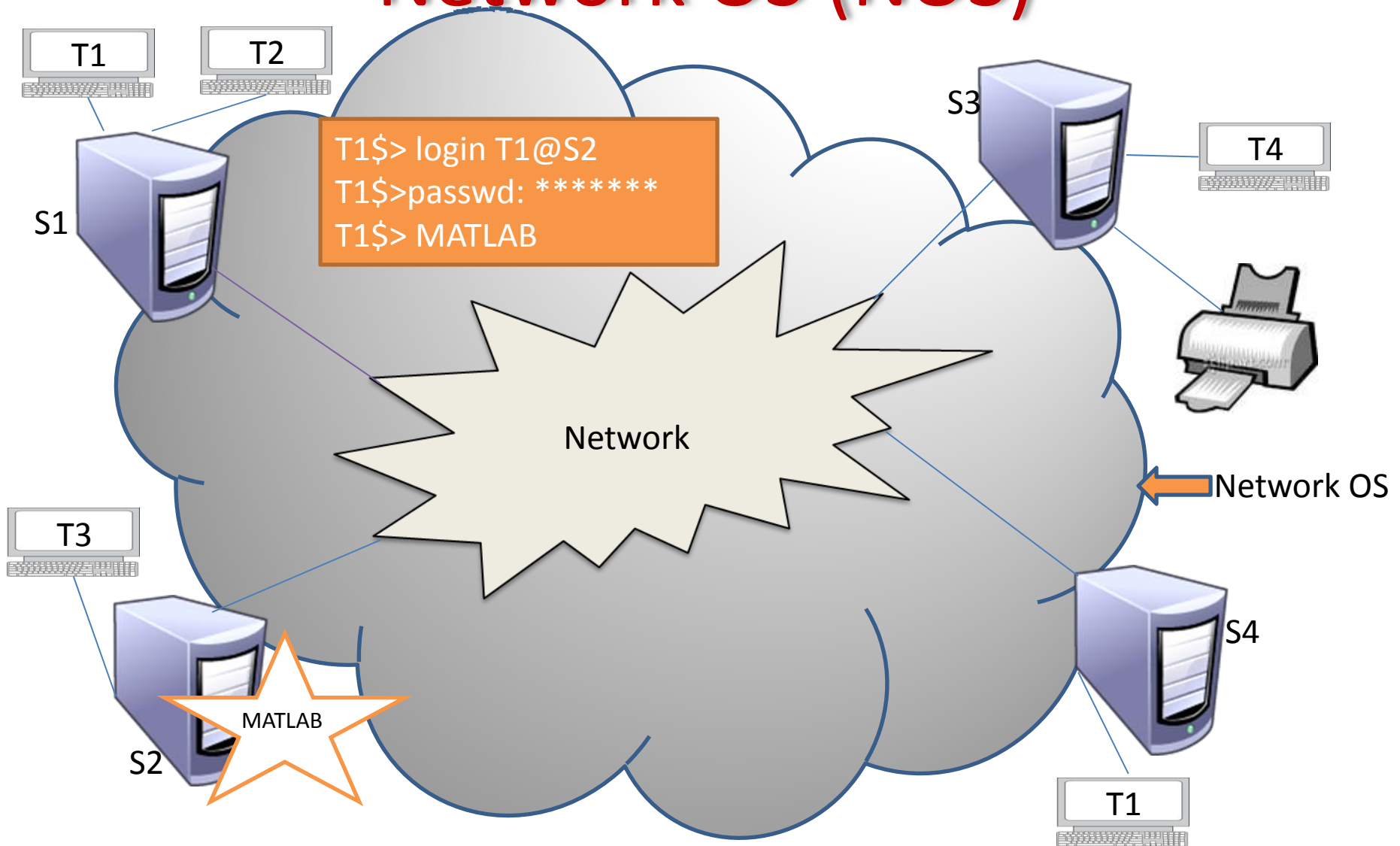
Centralized OS



Evolution of Modern OS

- Second generation OS
 - System :
 - Network OS
 - Characteristics :
 - Remote access
 - Information exchange
 - Network browsing
 - Goals :
 - Interoperability – sharing of resources between the systems.

Network OS (NOS)



Accessing of remote servers, remote high speed printers over network

Evolution of Modern OS

- Third generation OS

- System :

- Distributed OS

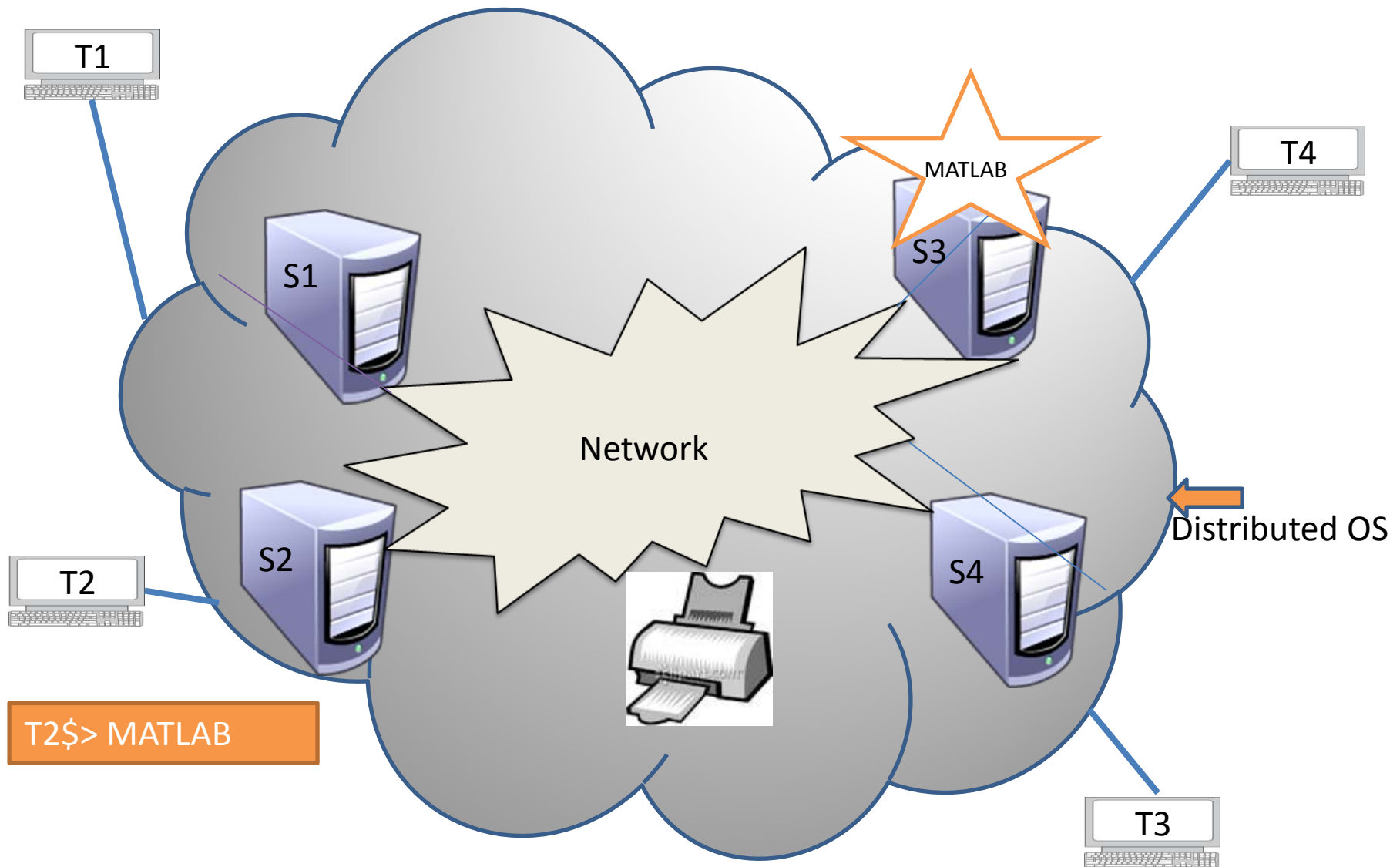
- Characteristics :

- Global view of computational power, file systems, name space,...etc.

- Goals :

- Single computer view of multiple heterogeneous computer systems

Distributed OS (DOS)



Single computer view of multiple heterogeneous computer systems

Differences between NOS and DOS

- NOS

- User need to login explicitly to access the remote resources
- User need to know whereabouts of the resources
- No implicit sharing of loads
- Full local autonomy at each system

- DOS

- No explicit login to the system to access any resources
- Gives the illusion of having all the resources locally available
- Sharing of loads between nodes (load balancing)
- Availability & Reliability is more

Evolution of Modern OS

- Fourth generation OS
 - System :
 - Cooperative autonomous system - CAS
 - Characteristic :
 - Cooperative distributed applications
 - Goals :
 - Cooperative work

Differences between DOS and CAS

- **DOS**

- Top down design approach
- Top level services are specified. It is then decomposed and implemented as low level services.
- No legacy system is involved.

- **CAS**

- Design approach is bottom up
- Existing services are integrated in possible way to form new services.
- Objective here is to develop the distributed system involving legacy system

Distributed Computing System

- Multi processor system
- Processors are geographically apart
- Communication is by message passing
- Coordination among the processors to perform the specific task.

Advantages of DCS over Centralized System

- **Speed:** 100 CPUs will have 100 times the speed of single processor ideally.
- **Inherent distribution of applications:** Some applications are inherently distributed.
 - For example, a bank may have many branches with the computing systems distributed across the geographical region to cater the local need. However, they need to coordinate for global need like *accounting across the banks*.
- **Robustness:** It is viewed with following metrics:
 - Availability: Probability that system is up at any given time interval.
 - Reliability: Probability that system is up at any point of time.
 - Both Availability and Reliability are high in DCS
- **Incremental growth:** Incrementally adding of resources will be gradually visualized performance wise.

Disadvantages of DCS over Centralized System

- **Software:**
 - Would be complex
- **Network problem:**
 - Network saturation
 - Malfunctioning of network
- **Security:**
 - Possibility of security violation since the private data are visible to others over the network.

Design Goals of DCS

- **Efficiency:**
 - **Bottleneck:** Communication delay, load balancing, number of messages for distributed algorithms
- **Flexibility:**
 - This refers to the friendliness of the system. From the systems point of view, it includes modularity, scalability, portability and interoperability.
- **Consistency:**
 - Computation should give correct results irrespective of time at which the computation is done for the same input conditions.
- **Robustness:**
 - The system should perform effectively and consistently in spite of failures and attempted security violations.

Design Goals of DCS

- **Scalability:**
 - This refers to the issue that the growth of the system should not result in degraded performance or unavailability.
 - Scalable resources are – bandwidth, storage, processing power...etc.
- **Compatibility:** Three levels of compatibility are possible
 - **Binary level:** same binary code can be executed at all nodes.
 - **Execution level:** same source code can be compiled and linked, and executed on any system
 - **Protocol level:** It achieves interoperability by acquiring system components to support common set of protocol.

Transparencies in DCS

- **Access transparency:**
 - Local and remote objects should be accessed in a uniform way. User should not find any difference in accessing local and remote objects.
- **Location transparency:**
 - Objects are referred by logical names which hide the physical location of the objects. For example, a network printer connected to a server **S1** on LAN **L1** is referred by the name associated with that printer and the exact location of the printer is invisible to the user.
- **Migration transparency:**
 - Movement of object (migration) from one system to other is invisible to user. Load balancing is one among many reason for migration of objects.
- **Concurrency transparency:**
 - Sharing of objects without interference. The same data may be referred by different applications. Performing of concurrency control to ensure the consistency of data should be invisible to the user.

Transparencies in DCS

- **Replication transparency:**
 - Replica of files and data are transparent to the user. One of the reason for replication is to ensure 'robustness' design goal.
- **Parallelism transparency:**
 - A user task may be scheduled for execution at different node/system which is invisible to the user. The reason for scheduling different node is to ensure 'efficiency' design goal.
- **Failure transparency:**
 - Graceful degradation in the performance when ever there are system failures.
- **Size transparency:**
 - Addition/deletion of resources should not effect the execution of task.
- **Revision transparency:**
 - Software revisions in the system are not visible to the user.

Relationship between Design Goals and Transparencies

- Design Goals

- Efficiency

- Flexibility

- Consistency

- Robustness

- Transparencies

- Concurrency
- Parallelism

- Access
- Location
- Migration
- Size
- Revision

- Access
- Replication
- Performance

- Failure
- Replication
- Size
- Revision

Fundamental Issues in DCS

- **Global state detection**
 - It is impossible to get the global up-to-date information about DCS due to
 - Lack of global memory
 - Lack of global clock
 - Unpredictable message delays
 - Global state of DCS is important for the consistency check
- **Ordering of events**
 - Due to lack of global clock, ordering of events across the systems in DCS is an issue
- **Naming**
 - A server needs to be identified in order to use its service.
 - A server can be identified using name, physical address or its service.
 - To handle the transparency issues need to map the physical name to the logical name.

Fundamental Issues in DCS

- **Inter-process communication**
 - Message passing communication
 - Request – reply communication
 - Transaction communication
 - Group communication
- **Inter-process synchronization**
 - Distributed mutual exclusion
 - Leader election
 - Agreement problems
- **Resource management**
 - **Data migration**
 - Distributed file system
 - Distributed shared memory
 - **Computation migration**
 - Distributed scheduling
 - Remote Procedure Call

Fundamental Issues in DCS

- **Fault tolerance**
 - Atomic execution of transactions
 - Replication management
 - Check pointing and recovery
- **Security**
 - Secrecy of data (Cryptography): Unauthorized access prevention
 - Authentication: Who are you?
 - Verification of sender (Digital signature): Message sent by X has really been sent by X.

Summary

- Definition, Basics of Distributed Computing is discussed.
- Differences between Distributed OS and Network OS is outlined.
- Requirements in terms of design goals, transparencies and fundamental issues in a Distributed Computing System is discussed.

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